

	Type	Hits	Search Text
85	BRS	1314378	motor.ab,clm,ti.
86	BRS	1145	((determin\$3 or calculat\$3) near3 inertia).ab,clm,ti.
87	BRS	372	motor.ab,clm,ti. and (((determin\$3 or calculat\$3) near3 inertia).ab,clm,ti.)
88	BRS	7	((determin\$3 or calculat\$3) near3 inertia with current with angular adj acceleration)
89	BRS	61	((determin\$3 or calculat\$3) near3 inertia with angular adj acceleration)
90	BRS	28	motor.ab,clm,ti. and (((determin\$3 or calculat\$3) near3 inertia with angular adj acceleration))
91	BRS	21	(motor.ab,clm,ti. and (((determin\$3 or calculat\$3) near3 inertia with angular adj acceleration))) not (((determin\$3 or calculat\$3) near3 inertia with current with angular adj acceleration))
92	BRS	564	347/37.ccls.
93	BRS	90	400/283.ccls.
94	BRS	4177	(determin\$3 or calculat\$3) near3 (inertial or inertia)
95	BRS	839	(347/37 or 400/283).ccls.
96	BRS	0	((determin\$3 or calculat\$3) near3 (inertial or inertia)) and ((347/37 or 400/283).ccls.)

	DBs	Time Stamp	Comments
85	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 15:57	
86	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:32	
87	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:01	
88	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:14	
89	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:15	
90	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:14	
91	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:31	
92	USPAT; US-PGPUB	2004/01/29 16:	
93	USPAT; US-PGPUB	2004/01/29 16:	
94	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/30 09:48	
95	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:33	
96	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/01/29 16:33	

	Error Definit	Errors
85		0
86		0
87		0
88		0
89		0
90		0
91		0
92		0
93		0
94		0
95		0
96		0

	Type	Hits	Search Text
97	BRS	106113	(347/\$ or 400/\$).ccls.
98	BRS	56	((determin\$3 or calculat\$3) near3 (inertial or inertia)) and ((347/\$ or 400/\$).ccls.)
99	BRS	1	3931562.pn.
100	BRS	1	ep-659572-\$ did.
101	BRS	2526	(318/560 318/611 318/615 318/616 318/626 318/685).ccls.
102	BRS	2943	((determin\$3 or calculat\$3) near3 (inertial or inertia)) ((318/560 318/611 318/615 318/616 318/626 318/685).ccls.) and (((determin\$3 or calculat\$3) near3 (inertial or inertia)))
103	BRS	31	5159254.pn.
104	BRS	1	5159254.pn.
105	BRS	14	("4445779" "4483425" "4612489" "4621332" "4694229" "4806835" "4808895" "4843293" "4868475" "4914726" "4950090" "4961034" "4965501")
106	BRS	23	5159254.URPN.
107	BRS	0	jp-8331880-\$ did.
108	BRS	2	jp-08331880-\$ did.
109	BRS	2	jp-02093457-\$ did.
110	BRS	2	jp-02093547-\$ did.

	DBs	Time Stamp	Comments
97	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/01/29 16:34	
98	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/01/29 16:48	
99	USPAT	2004/01/29 16:	
100	EPO	2004/01/29 16:	
101	USPAT; US-PGPUB	2004/01/30 09:50	
102	USPAT; US-PGPUB	2004/01/30 09:50	
103	USPAT; US-PGPUB	2004/01/30 11:19	
104	USPAT; US-PGPUB	2004/01/30 11:	
105	USPAT	2004/01/30 11:19	
106	USPAT	2004/01/30 11:	
107	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:06	
108	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:35	
109	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:36	
110	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:41	

	Error Definit	Errors
97		0
98		0
99		0
100		0
101		0
102		0
103		0
104		0
105		0
106		0
107		0
108		0
109		0
110		0

	Type	Hits	Search Text
111	BRS	6	constant adj (speed or velocity) adj control same machining
112	BRS	0	constant adj (speed or velocity) adj control same machine near table
113	BRS	22	constant adj (speed or velocity) adj control with table
114	BRS	98	control\$4 with constant adj (velocity or speed) with (breaking or stop or stoppage) with acceleration

	DBs	Time Stamp	Comments
111	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:46	
112	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:47	
113	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:51	
114	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/02/02 09:53	

	Error Definit	Errors
111		0
112		0
113		0
114		0